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Improving cadastral Infrastructure with RTK GPS in Australia

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# **Improving Cadastral Infrastructure with RTK GPS in Australia**

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Australia**

**Key words:** Cadastre, Infrastructure, RTK, GPS, Geospatial Alliance Project (GAP)

## **SUMMARY**

Cadastral surveying is primarily concerned with the process of gathering evidence in the form of position information that is used to define the location of objects or land boundaries for the purposes of identifying ownership and/or the value of land parcels. The advent of Global Navigation Satellite Systems (GNSS), such as the Global Positioning System (GPS), has revolutionised the way 3-dimensional positions are determined and GPS surveying techniques, particularly Real Time Kinematic (RTK), are increasingly being adopted by cadastral surveyors.

Due to the size of the Australian continent, the density of established (i.e. valid) survey marks varies considerably across the country, and there are areas where a higher density of established marks is desired. This paper presents a methodology for using RTK GPS observations to improve the existing cadastral survey control infrastructure, based on an extensive survey covering Junee Shire Council in NSW carried out as part of the Geospatial Alliance Project (GAP).

A large number of already established survey marks were occupied, facilitating an investigation of the accuracy achieved with the RTK GPS technique. Comparison of the RTK-derived positions of the established marks against their published values showed an accuracy (RMS) of 11 mm in the horizontal and 34 mm in the vertical component ( $1\sigma$ ). The relative accuracy of the RTK GPS results was investigated by performing bearing and grid distance calculations between a subset of established marks. Of particular interest were short distances routinely encountered by cadastral surveyors, i.e. less than 300 m, and it was shown that the results agreed very well with the values derived from the state's survey control database (SCIMS), easily meeting accuracy specifications and NSW survey regulation requirements.

Of the 128 unestablished marks (Class U) surveyed, 55% permitted upgrade to established mark status with a classification of C, while the quality of the remaining marks was updated to Class D or E. Ground observations obtained from Deposited Plans (DPs) provided valuable additional information for the adjustment. The results show that the RTK GPS technique is well suited to improving survey control infrastructure for cadastral surveyors as well as having the potential to detect erroneous DP information.

# Improving Cadastral Infrastructure with RTK GPS in Australia

Volker JANSSEN, Thomas GRINTER, Craig ROBERTS and Michael TROTH,  
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## 1. INTRODUCTION

Cadastral surveying, or land surveying, is primarily concerned with the process of gathering evidence in the form of position information that is used to define the location of objects or land boundaries in a geographic area for the purposes of identifying ownership and/or the value of land parcels. This information supports a jurisdiction's land administration, conveyance or land registration system and is critical in order to establish and maintain a digital cadastral database (DCDB).

In NSW, the Survey Control Information Management System (SCIMS) contains coordinates and related metadata information for survey marks established under the direction of the NSW Surveyor General and is maintained by the NSW Land and Property Management Authority (LPMA), formerly the NSW Department of Lands (Lands), for the purposes of cadastral boundary definition, engineering surveys, mapping and a variety of other spatial applications (Lands, 2009b).

The terms class and order are familiar to all surveyors and geodesists. The class is a function of the planned and achieved precision of a survey network, dependent on the design, survey practices, instrumentation and reduction techniques used. The order is a function of the class, the conformity with respect to the existing control network and the precision of any transformation process that may be required. Table 1 lists the classes applicable for horizontal survey control in Australia. Classes for vertical control are assigned similarly, distinguishing between levelled and non-levelled marks. Detailed definitions can be found in ICSM (2007).

Table 1: Horizontal survey control mark classes used in Australia (ICSM, 2007).

Point class	Typical applications
3A	Special high precision surveys
2A	High precision national geodetic surveys
A	National and state geodetic surveys
B	State survey control networks
C	Survey coordination projects
D	Approximate and lower order surveys
E	Approximate and lower order surveys
U	Unknown or unreliable

Established survey marks are classified as Class C or better in their horizontal position, reflecting sufficient redundancy and checks to guarantee the accuracy of the coordinates (ICSM, 2007; Lands, 2007). While SCIMS also contains lower quality survey marks, only established marks can be used for cadastral surveys. Understandably, due to the size of NSW,

the density of established survey marks varies considerably across the state and there are areas where a higher density of established marks is desired, particularly in regional urban areas.

The advent of Global Navigation Satellite Systems (GNSS), such as the United States' Global Positioning System (GPS), Russia's GLONASS, the European Union's Galileo and China's Compass, has revolutionised the way 3-dimensional positions are determined on and above the Earth's surface. Once initialised, Real Time Kinematic (RTK) GPS becomes a high precision coordinate generator and real world digitiser with the ability to significantly enhance productivity.

Roberts (2005) presented practical considerations for cadastral surveyors using RTK GPS and pointed out the following benefits of the technology:

- Usefulness in finding existing survey marks.
- Positions can be measured in the field in real time and distances derived to compare with plan distances.
- Ability to brace a traverse in difficult terrain where traversing techniques would require many setups with short lines to overcome hills or heavy tree cover, potentially improving loop closure accuracy significantly by reducing the number of setups and short lines.
- Ability to connect to existing survey control over distances considered unfeasible using traversing techniques.
- Ability to easily survey irregular natural boundaries.

LPMA has since revised the Surveying Regulation (Lands, 2006) to permit RTK techniques to be used over short distances by cadastral surveyors. In order to accommodate the coordinate accuracy achieved by GNSS (i.e. 10 mm + 1 ppm), the acceptable accuracy for distance measurements was redefined to 10 mm + 15 ppm at a confidence interval of 67% ( $1\sigma$ ). The growing CORSnet-NSW infrastructure (Lands, 2009a) utilises the internet to broadcast correction data which is accessed by users, e.g., via the Next-G mobile phone network. This is a more reliable communications medium than UHF radio, particularly in metropolitan regions. These developments, coupled with the improved usability of modern GNSS equipment, have seen GPS surveying techniques, particularly RTK, being increasingly adopted by cadastral surveyors.

RTK GPS techniques have also been investigated by LPMA for upgrade of the DCDB to survey accuracy in certain regions. Watkins (2007) conducted a case study in the Penrith area to determine the optimal number of control marks required for a given area in order to produce a survey accurate DCDB.

LPMA is promoting the use of GNSS techniques and has stated that it may decide to update SCIMS with RTK-derived coordinates at an established accuracy (Class C only), if observations to the mark have been made from three independent occupations using at least two separate base stations set on existing established SCIMS marks or surveyed in as part of the primary network (Lands, 2007). Since RTK observations produce radiations, careful

network design and redundancy are required to achieve an acceptable control survey outcome (ICSM, 2007).

This paper demonstrates how the RTK GPS technique can be utilised to improve the survey control mark infrastructure available to cadastral surveyors by determining high quality 3D positions for an update of the state's survey control database.

## 2. STUDY AREA AND OBSERVATIONS

### 2.1 The GAP Project

In 2005, the Geospatial Alliance Project (GAP) was initiated as a consortium of five councils located in southern NSW, i.e. Bland Shire Council, Coolamon Shire Council, Junee Shire Council, Temora Shire Council as well as Goldenfields Water County Council, which includes the aforementioned council areas (Figure 1). The aim of GAP is to provide best practice spatial information and management services to the alliance members, including spatial data capture, management and maintenance, Geographic Information System (GIS) capabilities, staff training, technical support and building awareness of spatial information.

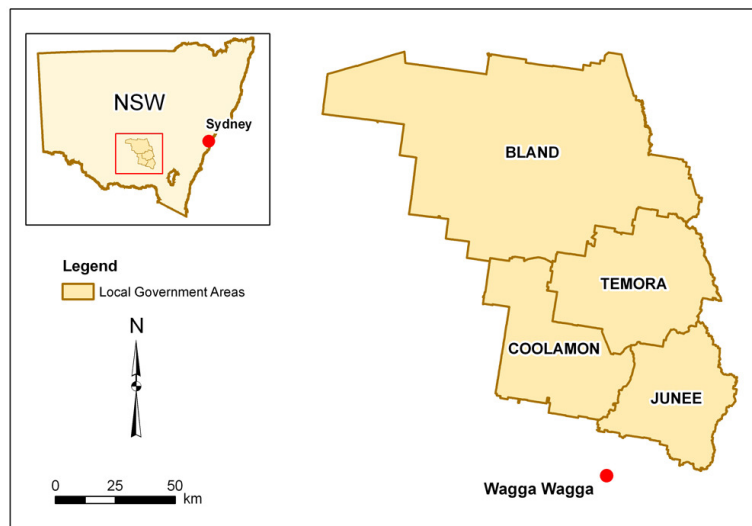


Figure 1: Local government areas involved in the GAP project.

GAP identified the need for an upgrade of survey control marks across the four shire council areas. While numerous survey control marks existed, a large number of these were classified as not established (i.e. less than horizontal Class C), making them unusable for cadastral surveys. In order to address this problem and generate an improved foundation for cadastral connections, a multi-year survey (2008-2011) was designed to observe all existing survey marks in the four shire council areas with RTK GPS technology, aiming to upgrade as many unestablished marks as possible to established marks in SCIMS and thereby supporting upgrades to the digital cadastral database (DCDB), engineering and photogrammetry control.

The already established marks were to be used to investigate the quality of the survey and the methodology adopted for the cadastral infrastructure upgrade.

## 2.2 Study Area and Observations

This paper presents the results from the GPS survey covering Junee Shire Council (Figure 2), an area of about 2,030 km<sup>2</sup>, and details the procedure adopted for the SCIMS update process. RTK GPS observations were conducted by a third party after basic training between 15 January and 27 August 2008 using a typical single-base RTK scenario consisting of two (identical) dual-frequency GPS receivers operating at a sampling rate of 1 second and utilising a UHF radio link. The elevation mask for RTK processing was set to 13°, and relative U.S. National Geodetic Survey (NGS) antenna phase centre variation models were applied.

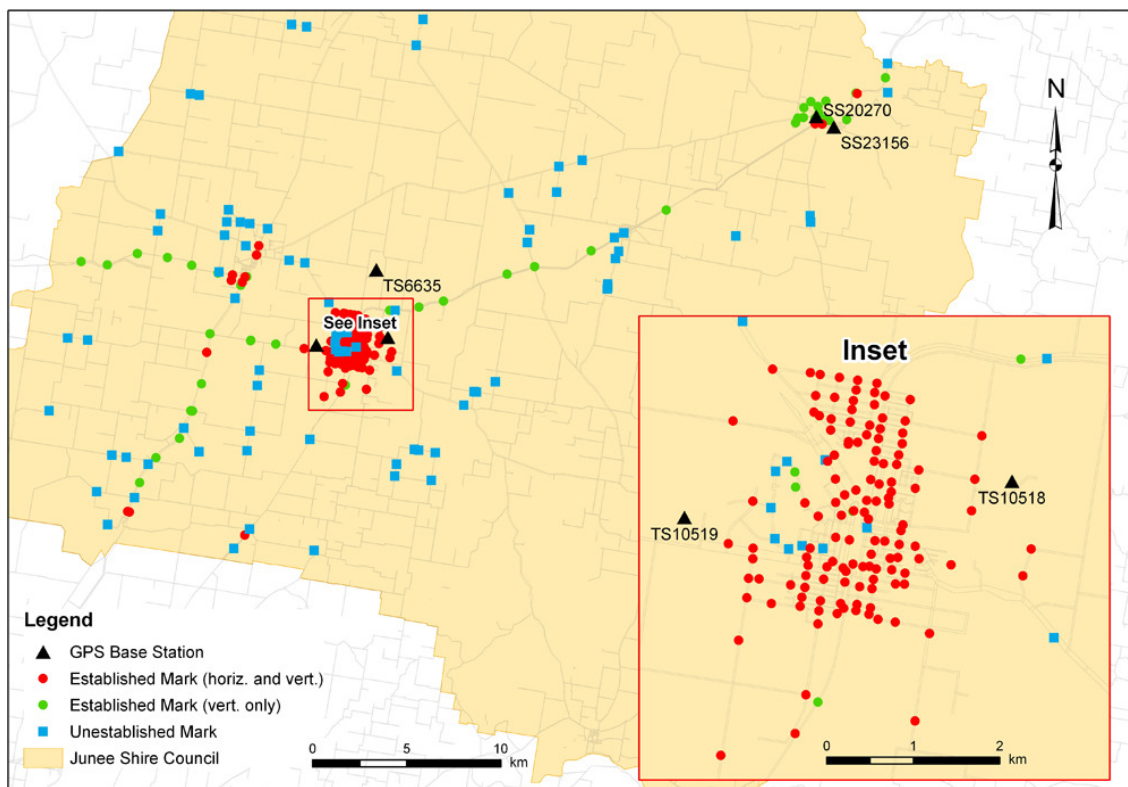


Figure 2: Survey marks occupied with GPS in Junee Shire Council.

Of the 269 marks occupied, 141 were already established in both horizontal and vertical position, while 43 were established in the vertical component only. It should be noted that the number of already established marks occupied is far lower in the other council areas. The relatively high number of established marks observed in the Junee Shire Council allowed several comparisons to be performed in order to investigate the quality of the survey and the methodology adopted for the cadastral infrastructure upgrade. Five of the established marks (TS6635, TS10518, TS10519, SS20270 and SS23156) were utilised as RTK base stations and radiations were observed to all points in range, resulting in baselines between 0.2 km and 20

km in length. Each point was observed several times (on different days) for at least 180 epochs, while three radiations to urban marks and two to rural marks were attempted. Up to six baselines were connected to each point, providing a high level of redundancy in most parts of the network.

All RTK rover observations were taken with a fixed 2-metre pole attached directly to the antenna, using a tripod for stability. The base station setups consisted of a tribrach and small (15 cm) extension pole on a pillar, with the exception of SS20270 and SS23156 where a tripod was used. Only ambiguity-fixed solutions were recorded. Site calibrations were not performed, allowing the raw data to be used.

### 3. DATA PROCESSING AND ANALYSIS

This section details the procedure adopted for data processing and analysis in order to determine high quality coordinates for the SCIMS update and to investigate the quality of the GPS-derived results.

#### 3.1 Network Adjustment

The adjustments are based on the baseline vectors exported from the commercial GPS processing software package utilised, rather than the RTK-derived coordinates. The application of local rotations and scale changes during processing was not necessary. The observed ellipsoidal heights were transformed to the Australian Height Datum 1971 (AHD71) by applying the AUSGeoid98 (Featherstone et al., 2001).

##### 3.1.1 Minimally Constrained Adjustment

The GPS dataset consisted of two unconnected sections. Firstly, a minimally constrained adjustment was performed holding only one base station in each section fixed (TS6635 and SS20270). The network was processed using Geolab 2001 version 2001.9.20.0 (Microsearch Corp, 2008) and initially consisted of 269 stations and 776 separate GPS baselines.

The initial observation weightings for the minimally constrained adjustment are summarised in Table 2. Geolab combined these with the RTK baselines' variance-covariance (VCV) information to produce final baseline component weights.

Table 2: Initial GPS baseline weighting.

	STD	ppm	Centring from	Centring to
<b>Horiz. component</b>	5 mm	0.7	1.5 mm	1.5 mm
<b>Vert. component</b>	5 mm	0.7	2.0 mm	2.0 mm

The statistical results of the minimally constrained adjustment for the highly radial survey were used to check for any gross errors in the network. After investigation, 23 baselines with unrealistically large residuals had to be removed, constituting about 3% of the observations. The resulting adjustment failed with a variance factor (VF) of 1.31, flagging 13 outliers which

were analysed and indicated contradictory GPS observations. These flagged residuals were noted and further analysed in the fully constrained adjustment. It should be noted that the standard deviations of the GPS observations used in the minimally constrained adjustment were too optimistic and therefore revised in the fully constrained adjustment.

### 3.1.2 Fully Constrained Adjustment

In addition to the five base stations (all classified horizontally as 2A0, i.e. Class 2A and Order 0), 141 stations were held fixed in the horizontal component (Table 3). In a first adjustment run, only the stations classified as 2A0 and A1 were held fixed, and the coordinates of a sample group of about 20 points were investigated. In a second run, the stations classified as B2 were also held fixed, and the resulting coordinates of the sample set were compared to their initial values. Since all differences remained below 10 mm, the fixed B2 control was left in the adjustment, allowing it to be highly constrained. Due to the adjustment being based on radiations, this is highly desirable when additional ground observations are to be added. It should be noted that there was no existing C3 horizontal control in the study area.

Table 3: Horizontal constraints.

Point class/order	No. of fixed stations
2A0	9
A1	61
B2	76

The network contained 184 marks with AHD71 heights of C3 or better, resulting in an orthometric height constraint for 68% of the stations. The weighting of these orthometric heights was based upon the marks' class and order in SCIMS (Table 4). It is worth noting that the GPS base stations were all classified as LCL3 (i.e. levelled) in the vertical component, except TS6635 which was B3 (i.e. GPS-derived with less than ideal control).

Table 4: Orthometric height constraints.

Point class/order	Uncertainty
LAL1	1 mm
LBL4	1 mm
LCL3	1 mm
B2	10 mm
B3	30 mm
C3	30 mm

Initially the GPS observation weightings listed in Table 2 were applied, holding all of the established marks (Class C or better) within the adjustment fixed horizontally and constrained vertically. It was determined that the GPS observation weightings were too optimistic and had to be loosened, so a new weighting was devised based on a combination of the manufacturer's specifications and previous RTK GPS experience (Table 5). The uncertainty in centring was revised to account for the 2-metre pole with attached bubble being used in the survey.



Table 5: Final GPS baseline weighting.

	STD	ppm	Centring from	Centring to
<b>Horiz. component</b>	10 mm	1.0	3 mm	5 mm
<b>Vert. component</b>	30 mm	3.0	3 mm	3 mm

In order to increase the number of unestablished marks to be upgraded to established marks, additional information obtained from Deposited Plans (DPs) was included to supplement the adjustment (see section 3.1.3).

The fully constrained adjustment passed with a VF of 0.99, however 18 residuals were flagged as outliers. In addition, a further 43 baselines were found to have high residuals of >50 mm. Analysis of the affected baselines identified a problem at one of the base stations. Large variations (>100 mm) were evident in the baseline observations utilising TS10518 as base station on 5-6 March compared to the other days of the survey. Due to a lack of additional information, the source of these variations (e.g. maladjusted tribrach or incorrect setup) could not be determined. Therefore, all baselines from TS10518 on 5-6 March were removed, fortunately amounting to only 39 observations which represents 5% of the survey. In addition, one ground observation obtained from a DP was removed due to large residuals. It is worth noting that it was later found that this particular observation was actually erroneous in the DP.

The final adjustment contained 714 GPS baselines and failed with a VF of 0.67, suggesting that a tightening of the observation uncertainties was required. However, the VFs for ellipsoidal and orthometric height were determined to be 0.91 and 0.81, respectively, and the result was therefore deemed satisfactory. Hence, no scaling of the VCV matrix by the VF was adopted.

Five residuals were flagged in the adjustment but were deemed acceptable since these referred to constrained orthometric heights. In all five cases, at least three GPS observations were made to each mark. The values agree with each other, but disagree with the orthometric height for the mark by up to 125 mm, indicating a possible incorrect orthometric height for these marks. However, further analysis of each mark is required to confirm this.

All of the 13 residuals that were flagged in the minimally constrained adjustment (see section 3.1.1) passed in the fully constrained adjustment due to the larger observation uncertainties applied. However, closer inspection revealed that the GPS observations to each of these flagged marks disagree. The observations were left in the adjustment but the larger residuals were later taken into account when the affected marks were assigned an order (see section 4).

Overall, the GPS residuals were relatively small, typically less than 50 mm in each Cartesian coordinate component. The residuals of the 88 ground observations obtained from DPs were typically less than 10" and 20 mm, comparing well with the accuracy of 10 mm + 15 ppm required for a distance measurement by Clause 25 of the Surveying Regulation 2006 (Lands, 2006).

### 3.1.3 Additional Information obtained from Deposited Plans

In order to add information to the GPS observations in the adjustment, ground observations obtained from Deposited Plans (DPs) were utilised. The observed directions and distances between the marks were reduced to the ellipsoid. One of the purposes of this project is to upgrade unestablished marks to established marks. In order to achieve this using GNSS surveying techniques, three baselines from at least two different base stations must be observed (Lands, 2009c). Adding an observed ground connection between marks to the adjustment, enabled us to upgrade many marks that were only observed twice by GPS.

In total, 88 observations from 31 DPs, connecting 66 points, were added to the fully constrained adjustment. The observation weightings are based on similar adjustments previously performed by LPMA (Table 6).

Table 6: Weighting of ground observations derived from DPs.

	STD	ppm	Centring from	Centring to
<b>Direction</b>	8"	–	2.5 mm	2.5 mm
<b>Distance</b>	10 mm	20	2.5 mm	2.5 mm

## 3.2 Absolute Accuracy: RTK vs. SCIMS on Established Marks

In order to investigate the absolute accuracy of the RTK GPS campaign and the presented methodology for cadastral infrastructure improvement, the calculated coordinates of all established marks in the survey were compared to their published SCIMS values. A constrained adjustment of the GPS network was performed, holding only the five GPS base stations fixed in the horizontal and constrained in the vertical component. The GPS observation weightings listed in Table 5 were applied, and no DP directions or distances were utilised.

As mentioned earlier, 141 of the surveyed marks were already established in both the horizontal and vertical component, while 43 were established only vertically. By running an adjustment that allows these established marks to float, a comparison can be made between the coordinates of these marks determined by the RTK GPS survey and their SCIMS values. Under the assumption that RTK GPS accuracy and the horizontal and vertical datums are relatively uniform across the study area, this will also give an indication of the quality of the presented methodology to upgrade unestablished marks using RTK GPS.

The adjustment achieved a VF of 0.41 and failed the chi-square test, suggesting that the input variances should be tightened. However, as this adjustment is being used for comparison purposes, this result was accepted. Two residuals were flagged but deemed acceptable since they referred to constrained orthometric heights, indicating a possible error in the orthometric height in SCIMS (cf. section 3.1.2).

Table 7 shows the differences between the GPS-derived coordinates and their SCIMS values. It is recognised that the differences may in part be due to the inferior quality of the

observations used to establish these marks in the era before satellite positioning, although routine NSW survey control practices were followed at the time. The comparison exceeded expectations with a Root Mean Square (RMS) of 11 mm in the horizontal and 34 mm in the vertical component ( $1\sigma$ ), indicating that the RTK GPS technique is well suited to improve survey control infrastructure for cadastral surveyors.

Table 7: Difference between RTK GPS and SCIMS coordinates.

	<b>Easting</b>	<b>Northing</b>	<b>Horizontal</b>	<b>Vertical</b>
<b>RMS</b>	7 mm	8 mm	11 mm	34 mm
<b>Min.</b>	-18 mm	-25 mm	0 mm	-65 mm
<b>Max.</b>	29 mm	36 mm	36 mm	137 mm

It should be noted that the difference in the vertical component exceeded +100 mm in seven cases. As previously mentioned, this indicates a possible problem with the orthometric heights of these marks given in SCIMS, as the GPS observations agree well with each other. Most of these marks are clustered in a group of four (B2, based on GPS observations in 1997/98) and a group of two (LAL1, optical levelling based on the same run), while the remaining mark is classified as LBL4 (i.e. optically levelled with less than ideal control). Further research is necessary in order to identify the cause of this discrepancy, which could, for instance, be due to local distortions in the geoid or weak levelling connections. However, this is beyond the scope of this paper. Removing these seven values reduced the RMS in the vertical component to 26 mm.

### 3.3 Relative Accuracy: RTK vs. SCIMS over Short Distances

The relative accuracy of the RTK GPS results was investigated by determining the bearing and grid distance between 50 established marks, based on the initial, unadjusted RTK-derived coordinates as well as the given SCIMS coordinates. In order to pay particular attention to short distances routinely encountered by cadastral surveyors, the selected dataset contained distances ranging from 28 m to 332 m. Table 8 summarises the differences between the RTK-derived and SCIMS-derived values, based on a total of 51 bearing and distance pairs.

Table 8: Difference between values derived from RTK GPS and SCIMS coordinates.

	<b>Grid Distance</b>	<b>Bearing</b>
<b>RMS</b>	9 mm	14"
<b>Min.</b>	-30 mm	-33"
<b>Max.</b>	14 mm	33"

It is evident that the values agree very well, with RMS values of 9 mm for the grid distance and 14" for the bearing ( $1\sigma$ ). Figure 3 illustrates the entire dataset (absolute differences) as a function of the distance between the two marks involved in the calculation. The Surveying Regulation 2006 stipulates the required accuracy for a distance measurement as 10 mm + 15 ppm or better at a confidence interval of 67% (Lands, 2006). This translates into 11 mm over 50 m and 14.5 mm over 300 m, and is easily met by the RTK GPS results. The bearing differences also show the consistency of the RTK-derived values. For instance, bearing errors

of 15" over 100 m, 10" over 200 m and 5" over 300 m result in horizontal position errors of 7.3 mm, 9.7 mm and 7.3 mm, respectively.

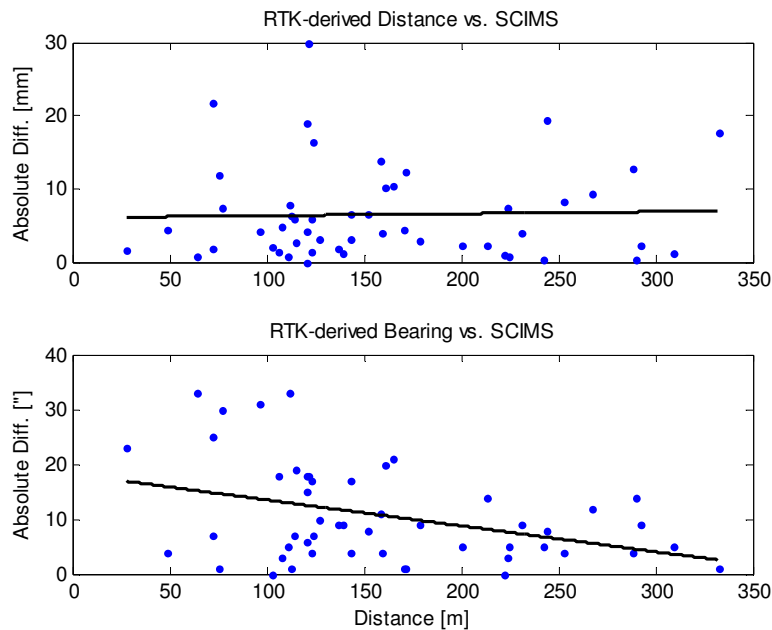


Figure 3: RTK-derived distances and bearings vs. SCIMS (absolute differences).

Linear trend lines are also shown in Figure 3, however it must be emphasised that these are not statistically sound and can therefore only give an indication. The accuracy of the RTK-derived distances is very consistent, reflecting, in part, the local homogeneity of the Geocentric Datum of Australia (GDA94) and the uniform atmospheric conditions encountered in the study area. It should be noted that a similar accuracy can be expected over longer distances calculated in the study area since the differences reflect the quality of the RTK GPS observations, which is influenced by the baseline length between each mark and the base station(s) utilised as well as the network geometry, and not the distance between the two marks involved in the distance calculation. As expected, the quality of the RTK-derived bearings improves over longer distances since errors in the horizontal position have a lesser effect on the calculated bearing.

#### 4. UPGRADE OF CADASTRAL SURVEY CONTROL

The main purpose of this study was to upgrade as many as possible of the observed unestablished marks to established marks in order to improve the survey control infrastructure available in the study area. According to the regulations, it is required that at least three baselines are observed from at least two separate base stations in order to upgrade an unestablished mark using RTK GNSS methods (Lands, 2006; 2007; 2009c).

It was determined that 55 marks met this requirement: 37 to be upgraded to Class C in both the horizontal and vertical components, and 18 to be upgraded in the horizontal component

(as they were already established in the vertical). However, five of these marks were excluded from the upgrade due to discrepancies in the GPS observations identified during the adjustment (see section 3.1.2). Therefore, 50 survey control marks met the upgrade criteria: 33 both horizontally and vertically, and 17 in the horizontal component.

A further 22 unestablished marks were observed twice with RTK GPS. By adding one or two ground observations obtained from DPs (see section 3.1.3), these also met the criteria to become established. One of these marks was excluded from the upgrade due to previously identified discrepancies in the GPS observations, leaving 21 additional marks to be upgraded to Class C (13 in both the horizontal and vertical components, and 8 horizontally only since they were already established vertically).

The remaining 51 unestablished marks were observed only once or twice with RTK GPS and suitable DP information was not available. The majority of these marks were initially classified as Class U in both the horizontal and vertical components, with eight marks being Class E either horizontally or vertically. Although these marks cannot be upgraded to established marks, it is possible to increase their class and order based on the GPS survey. All of the marks with two RTK GPS occupations were updated to Class D in both coordinate components (making them suitable for DCDB upgrades), while the five marks occupied only once were updated to Class E in both components.

The six unestablished marks that were initially excluded from the upgrade due to GPS observation discrepancies were updated to Class E in both components. Hence, all of the 128 surveyed unestablished marks could either be established to Class C (55%) or at least be updated to Class D or E (45%), resulting in a significant improvement of the cadastral survey infrastructure in the study area.

## **5. CONCLUDING REMARKS**

This paper has presented a methodology for using RTK GPS observations to improve the existing cadastral survey control infrastructure, based on an extensive survey carried out in Junee Shire Council as part of the Geospatial Alliance Project (GAP). Of the 128 unestablished marks surveyed, 55% were able to be upgraded to established marks of Class C, while the quality of the remaining marks was updated to Class D or E. Improvements in the GPS survey design would have enabled an even higher percentage of marks to be classified as established. Ground observations obtained from Deposited Plans (DPs) provided valuable additional information for the adjustment.

The large number of already established marks surveyed enabled a thorough analysis of the accuracy achieved with the RTK GPS technique. The RTK positions of the established marks were compared against their SCIMS values, exceeding expectations with an accuracy (RMS) of 11 mm in the horizontal component and 34 mm in the height component ( $1\sigma$ ). In addition, the relative accuracy of the RTK GPS results was investigated by determining the bearing and grid distance between a subset of established marks. Of particular interest were short distances routinely encountered by cadastral surveyors, and it was shown that the results

agreed very well with the values derived from SCIMS, easily meeting accuracy specifications stated in the Surveying Regulation 2006.

The RTK GPS technique is well suited to improving survey control infrastructure for cadastral surveyors and has the potential to detect erroneous DP information. The ongoing expansion and densification of Continuously Operating Reference Station (CORS) networks, such as GPSnet (Hale et al., 2007) and CORSnet-NSW (Lands, 2009a; White et al., 2009) will further improve position accuracy and RTK range capabilities by providing network RTK services (e.g. Janssen, 2009; Norin et al., 2009). This infrastructure will provide cadastral surveyors with increasingly fast and easy access to highly accurate survey control, eliminating the need for surveyors to operate their own base station and thereby improving productivity. The presented methodology for updating existing survey control marks based on RTK GPS observations will also benefit from the increased number of CORS across the state, potentially removing the need for a temporary base station.

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